

Progress in the Development of the Agent-based Dynamic Activity Planning and Travel Scheduling (ADAPTS) Microsimulation Model

Joshua Auld

Kouros Mohammadian

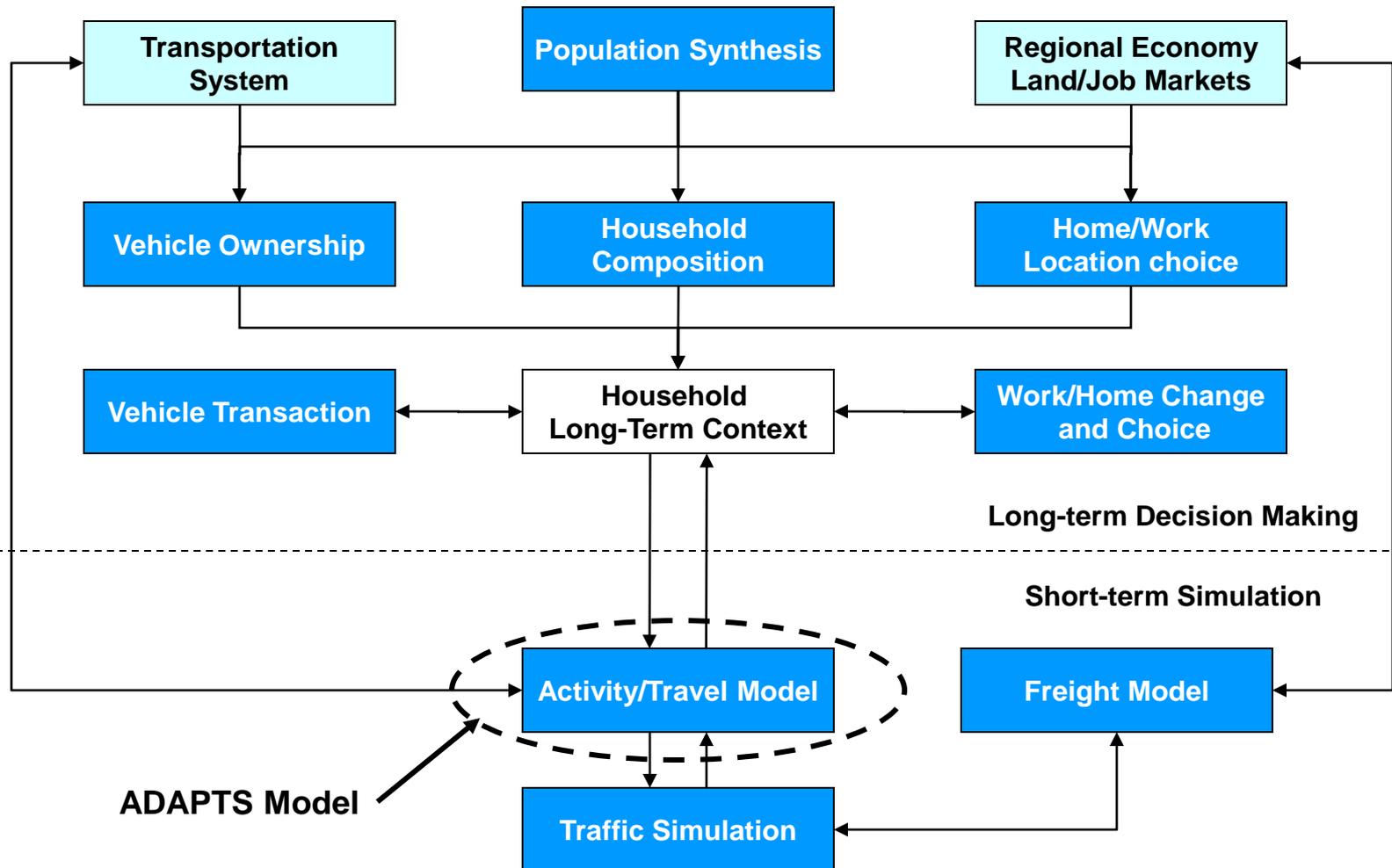
*Department of Civil and Materials Engineering
University of Illinois at Chicago*

*Presentation at the
Chicago Area Transportation Model User Group
June 2, 2010*

Overview

- Introduction and Motivations
- ADAPTS Framework
- Current work on the ADAPTS model
 - Activity generation
 - Activity planning strategies
 - Attribute planning (destination choice)
 - Activity scheduling
 - Integration with Traffic Assignment
- Pricing Simulation Results
- Discussion / Conclusions

Overall Integrated Land-Use Transportation Model Framework



Introduction and Motivation

Activity based modeling

- Activity-based modeling
 - Microsimulation models which develop individual activity schedules
 - Usually at the household or individual level
 - Pattern of activities and travel explicitly developed for entire population
- Advantages (from having more of a behavioral basis):
 - Can represent time very accurately
 - Represent response to policy changes very well
 - Explicitly captures trip chaining response
- Two dominant paradigms:
 - Econometric
 - Computational Process Model
- Currently lacking:
 - Representation of planning dynamics
 - Realistic activity planning
 - Integration with traffic simulation – usually done through feedback

Issues in Activity-Based Modeling

- Preset activity priority order:
 - Activities added to schedule and attributes picked in fixed order
 - In other models: activities added in order of assumed priority
 - Does not match observations from data (Roorda et al. 2005)

- Fixed order of attribute scheduling:
 - Ex: Party > Duration > Location > Mode > Time
 - Gives fixed dependencies in the decisions
 - Again, does not match actual scheduling process
 - seen in CHASE, OPFAST, UTRACS (our GPS survey), etc.)

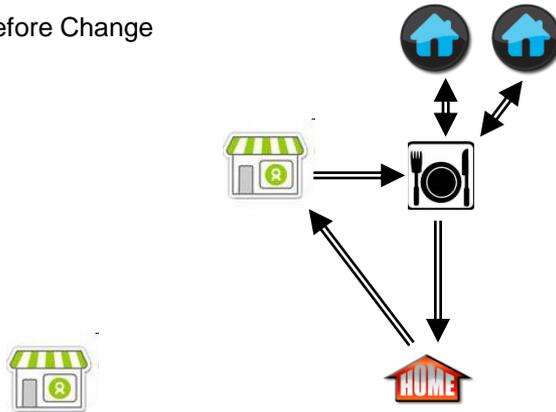
- Scheduling planning dynamics
 - Order of decisions can impact subsequent decisions
 - Impulsive/unexpected events in simulation or scenarios
 - Many have entire schedule generated then executed

- May lead to errors modeling behavioral-based policies

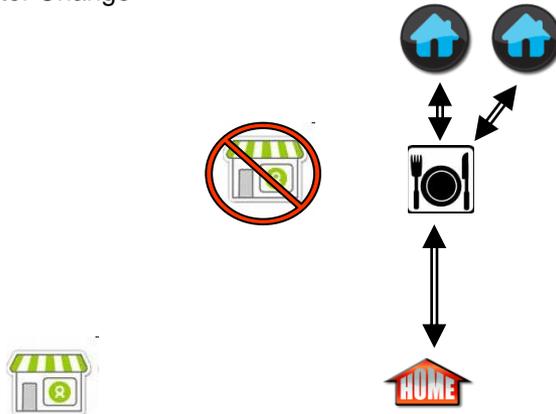
Scheduling Order Example

A) Impulsive Shop - Preplan Eat Out

Before Change

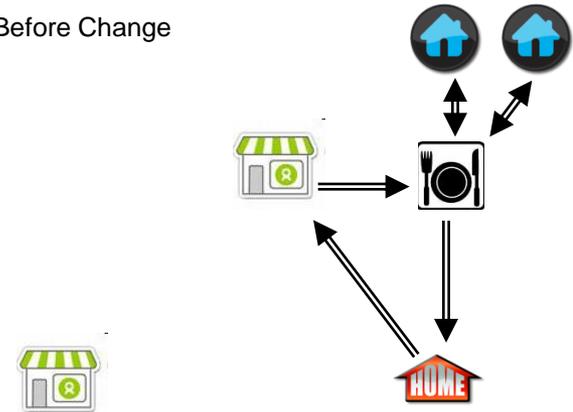


After Change

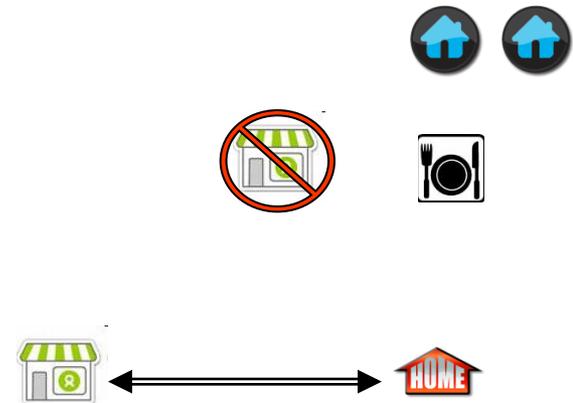


B) Preplan Shop - Impulsive Eat out

Before Change



After Change



Motivation for ADAPTS

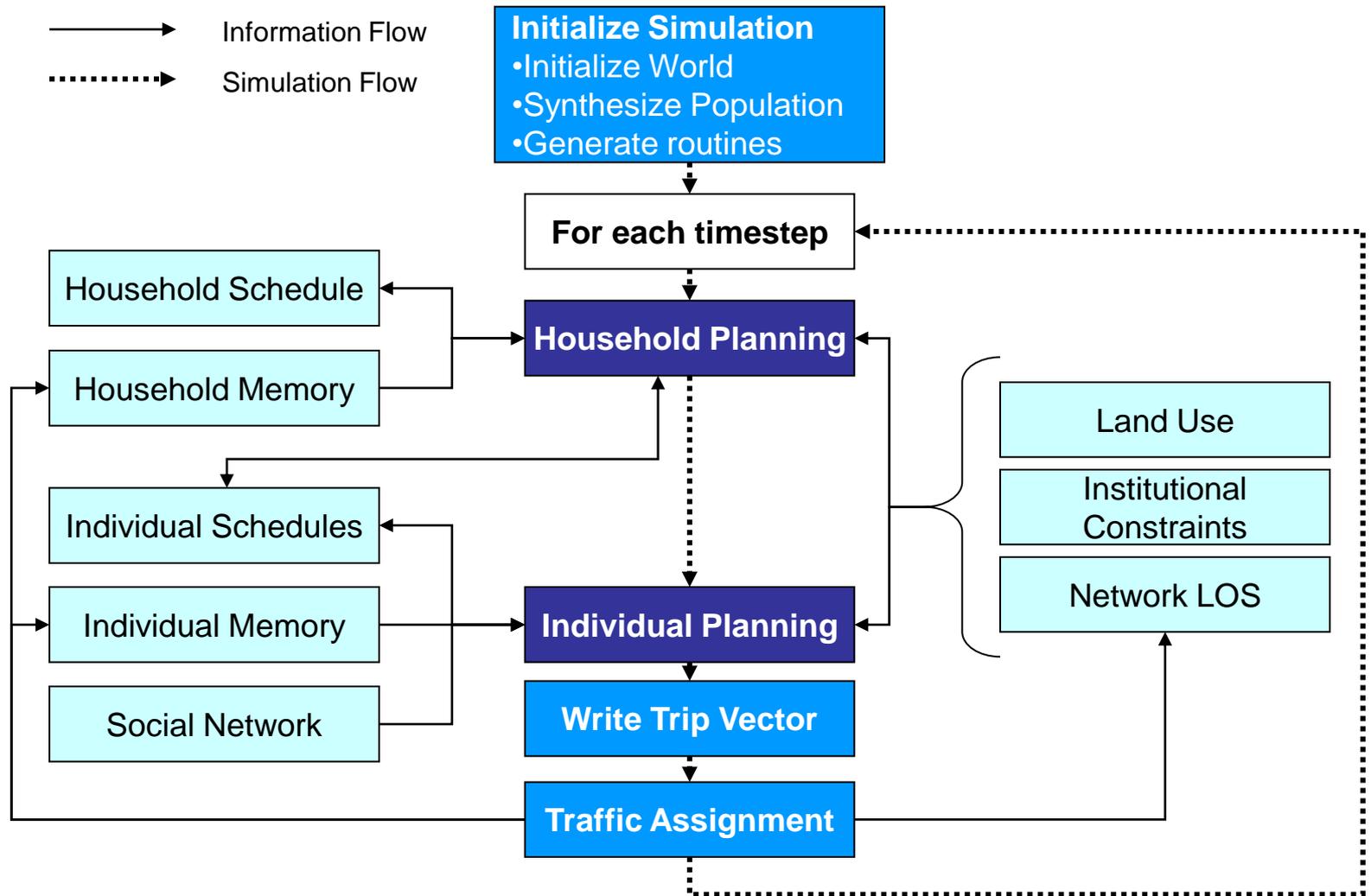
- When and how activity planning decisions are made can impact final daily activity pattern
 - In example, both situations start with same pattern
 - Small policy change creates large differences in pattern, depending only on activity planning
- ADAPTS: adds element of activity planning, to activity generation and activity scheduling
 - Simulation of planning steps
- Account for planning dynamics
 - when is each decision made in relation to other decisions, activities, schedule, etc.
- Represent macro-level changes from impacts of policies on planning dynamics at individual level

ADAPTS Model Framework

Framework - Introduction

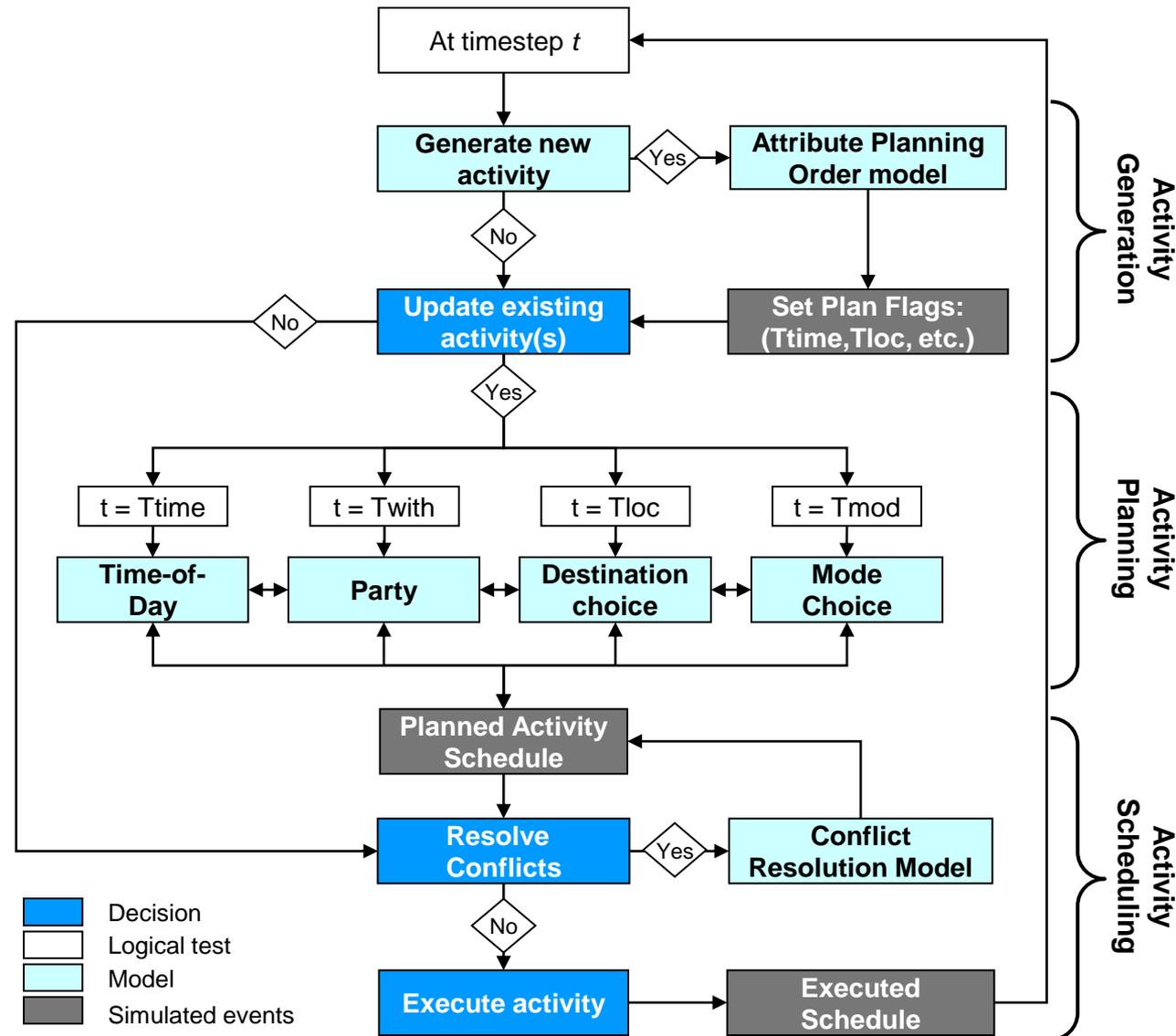
- ADAPTS scheduling process model:
 - Simulation of how activities are planned and scheduled
 - Extends concept of “planning horizon” to activity attributes
 - Time-of-day, location, mode, party composition
- Fits within overall framework of activity-based microsimulation model
 - Constraints from long-term simulation (land-use model)
 - Combined with route choice and traffic simulation
- Models being generated for Chicago region
 - Datasources: UTRACS (GPS) Survey, CMAP household travel survey, CMAP land-use database, Census 2000, CHASE, etc.

ADAPTS Simulation Framework

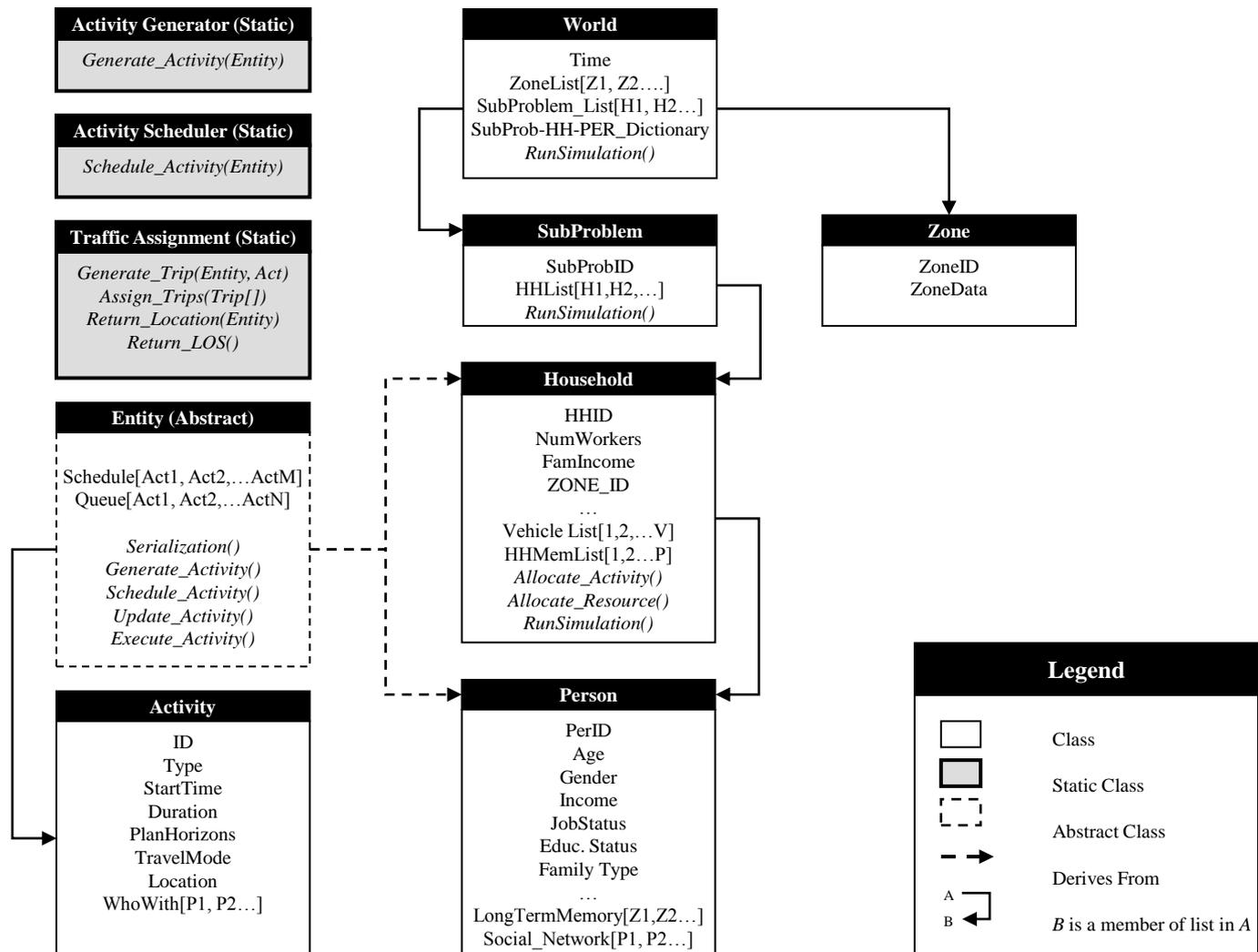


ADAPTS Planner/Scheduler

- ADAPTS planning and scheduling framework
- Handles at each timestep:
 - Generation
 - Planning
 - Scheduling
- Generation, planning and scheduling can occur at different times for same activity
- Core of the framework is the *Attribute Plan Order Model*



Framework: C# Simulation Objects



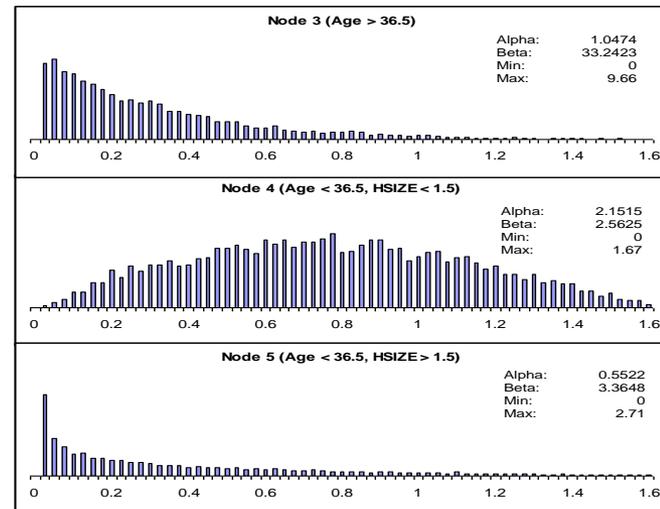
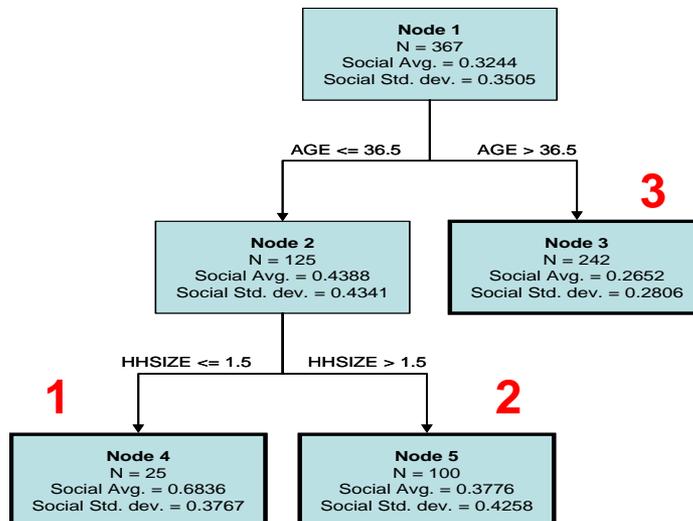
Completed Components of ADAPTS

- Rest of discussion will focus on core components of ADAPTS which have been completed
 - Activity Generation (1st Stage)
 - Activity Planning Strategies
 - Attribute Planning (Destination Choice)
 - Activity Scheduling
- Demonstration of current system

Activity Generation

Activity Generation

- Activity generation through set of decision trees
 - Classify HH/Person by socio-demographics
- Generation rates drawn from probability distribution fit at each node
 - Distributions estimated from 7-day CHASE data
 - Fit to Chicago 1-day survey through updating



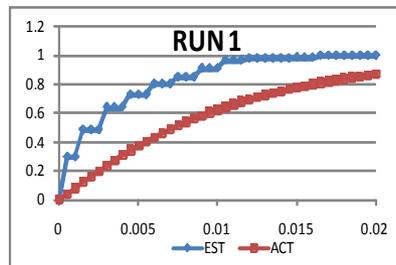
1

2

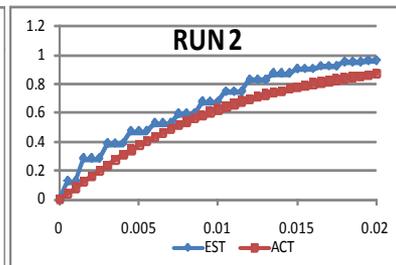
3

Activity Generation: Correction Factors

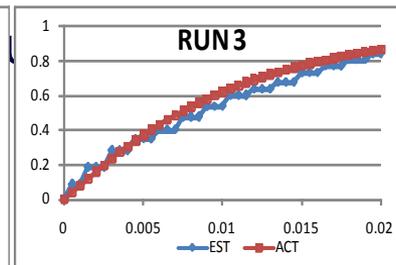
- Using observed generation rates gives incorrect results
 - Due to collisions (i.e. activity conflicts)
 - Activities split, postponed, deleted, etc.
- Unobserved planned activity generation
- Try to correct generation distributions through simulation:
 - $f_i^* = S(\lambda_i f_i)$, minimize $(f_i^* - f_i) \forall i \in \text{activity types}$
 - $\lambda_i f_i$ approximates unobserved planned activity generation
 - Must be solved simultaneously



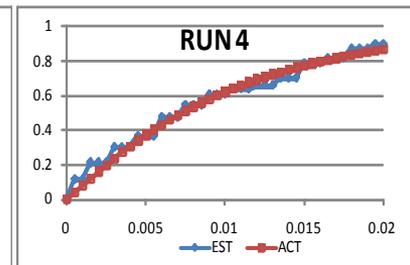
$\lambda_l = 1.0$



$\lambda_l = 1.26$



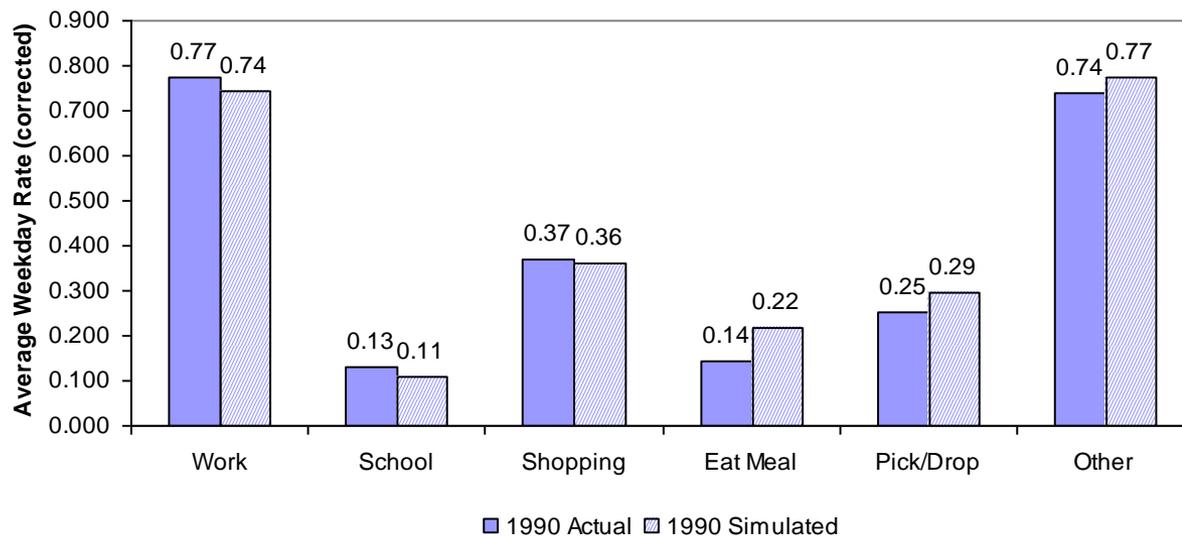
$\lambda_l = 1.53$



$\lambda_l = 1.45$

Activity Generation: Validation

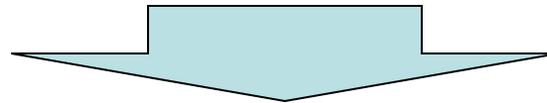
- Application to Chicago-region
 - Calibrated to 2007 data
 - Backcast validation to 1990 HHTS
 - Validated by activity-type, HH Type, etc.
- Currently updating to include generation dynamics
 - System of simultaneous hazard equations for generation



Activity Planning Strategies

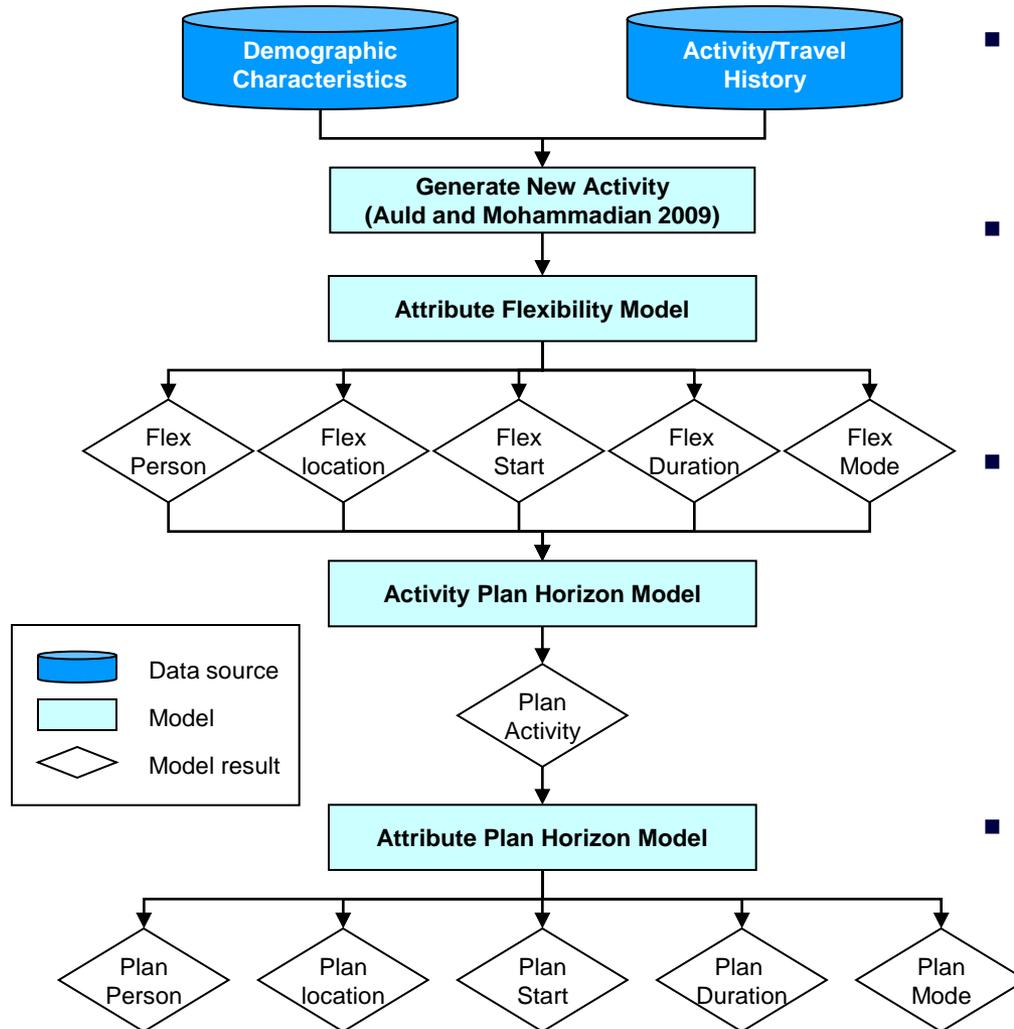
Activity Planning in ADAPTS

- Activities generated and planned dynamically
- Conditional decision making, dependent on
 - Past history
 - Current plans
 - Situation/resource/capacity/household constraints
- Need to know when activities/attributes are planned



- Activity planning order model
 - General categories of when activity generation and attribute planning occur in the schedule

Activity Planning Order Framework



- Assign plan horizon to each attribute
 - After activity generated
- Plan order model process
 - Assigns attribute flexibility
 - Get activity plan horizon
 - Attribute plan horizons
- Plan horizons for each attribute based on:
 - Attribute flexibilities
 - Activity plan horizon
 - General activity attributes
 - Socio-demographics, etc.
- Defines the *meta-attributes* of the activity attributes

Planning Models Discussion

- Estimated set of ordinal/multivariate probit models
 - All models have acceptable goodness of fit
 - Significant improvement over null models
 - Generally have parameters significant at 0.05 level
- Determines how activity flexibility/plan horizon impact attribute planning
 - More expected planning/scheduling effort => more preplanning
- Includes policy sensitive variables relating to:
 - Telework and flex scheduling
 - ICT usage rates
 - Generalized travel costs
 - Endogenous scheduling variables (average frequency, duration)

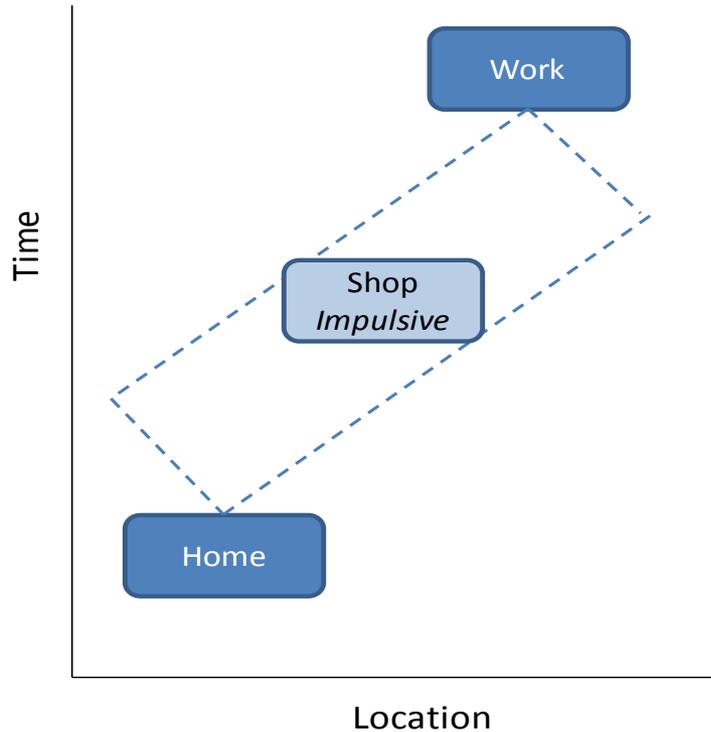
Destination Choice Modeling

Destination Choice

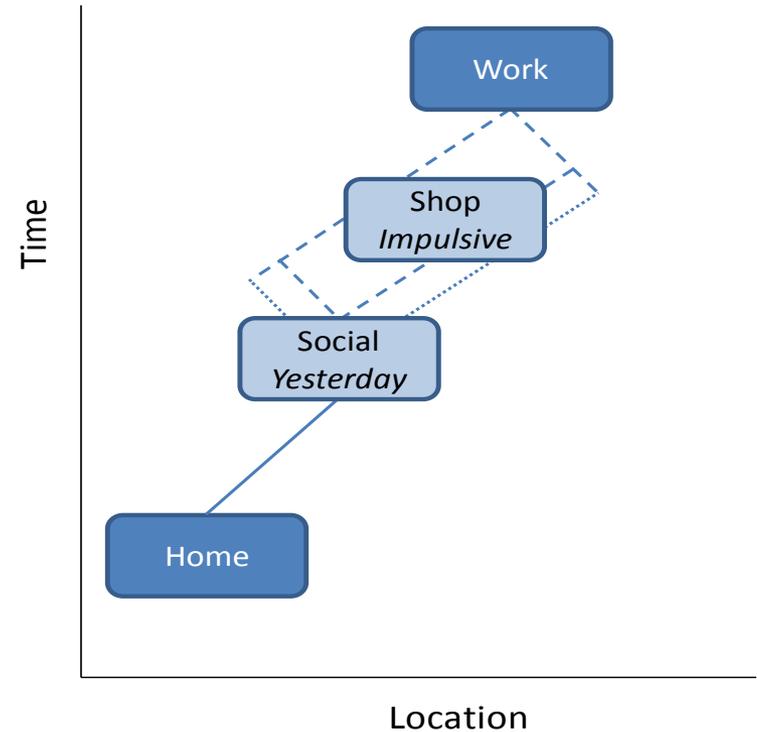
- Need conditional model of destination choice
 - Represent impact of planning dynamics
 - Core focus of ADAPTS development
- Planning influences indirectly through choice set
 - No need for a full set of conditional models
- Planning constrained destination choice
 - Observe what has already been planned before choice
 - Space-time constrains based on previous plan
 - In addition to constraints from fixed activities

Planning Constrained Destination Choice

(a) *Shop* planned first



(b) *Shop* planned after *Social*



-  Fixed activity
-  Planned activity
-  Constraint from Fixed Activity
-  Constraint from Modifiable Activity

Destination choice: Example

- Planning constraints determine the available time
 - Assuming known values for LOS between zones
 - Conditional choice set formation using available travel time
 - Depends on plan time of each individual attribute
- Planning constraints on *Shop* Activity:
 - If *Social* timing and location known
 - Travel time available = end of *Social* to start of *Work*, calculated starting from *Social* location
 - If *Social* location known
 - Travel time available = end of *Home* to start of *Work*, calculated starting from *Social* location less travel time from *Home* to *Social*
 - If *Social* timing known
 - Travel time available = end of *Social* to start of *Work*, calculated ending at the work location (no inbound trip to *Shop* used)
 - *Shop* location choice then constrains *Social* location choice

Destination Choice (continued)

- Choice set formed using plan-constrained prism
 - Importance sampling (on travel time, employment totals) of zones
 - Clearly requires planning data to determine choice set
- Use variety of Competing-Destinations model:

$$V_{in} = \beta_T T_{in} + \beta_I \ln(I_{in}) + \beta_R R_{in} + \sum_j^J \beta_j \ln(A_{ij}) + \sum_k^K \beta_k \ln(E_{ik}) + \sum_k^K \theta_k C_k + \ln\left(\frac{1}{p(i)}\right)$$

Where,

A_{ij} = Land use variables

E_{ij} = Employment variables

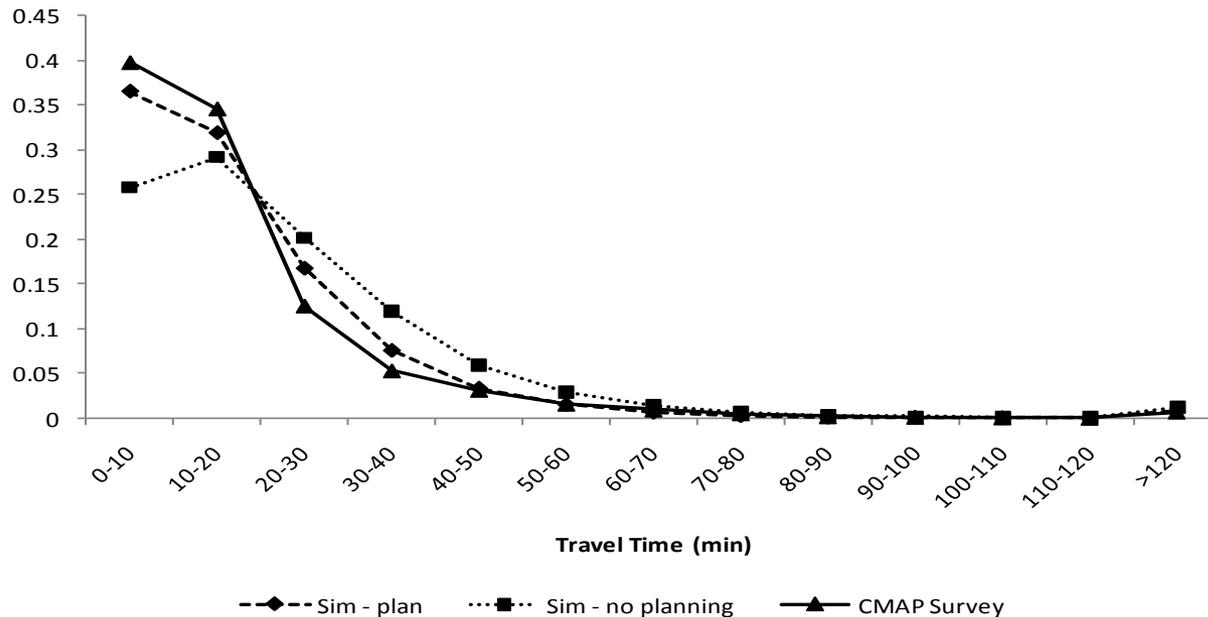
C_k = Competition/Agglomeration factor

$p(i)$ = Probability of zone being selected into choice set

$$C_k = \left(\frac{1}{N_{zone} - 1} \sum_{l \neq i}^{N_z} e_{lk} e^{\frac{-d_{il}}{\gamma}} \right)$$

Destination Choice - Validation

- Model estimated for Chicago using 2007 HHTS data
 - Simulated planning data using plan order model
- Compared to same model with no planning constraints on choice set formation
 - Trip time distribution much closer for plan constrained model
 - Higher aggregate R^2 (0.602 vs 0.571) over all activities



Activity Scheduling

Scheduling Rules - Overview

- Set of rules for scheduling randomly generated activities
- Attempts to resolve conflicts by modifying each activity
 - series of rules determine how modifications are made
 - System based on the scheduling rules found in TASHA model
- Includes results of conflict resolution model:
 - TASHA – conflict resolution based on heuristic rules
 - New rules – heuristic rules determine how conflict resolution strategy is implemented
 - Possible resolutions for two activities in conflict: delete original activity, modify original, modify conflicting, modify both
- New rules allow for the consideration of more complicated conflict types and deletion operations
- When activities can be truncated, each activity assumed to be truncated proportionally to duration

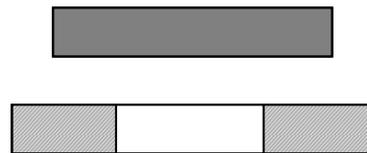
Scheduling – Overall System

- Based on conflict resolution model
 - Resolution strategy determines rules followed
- For all situations show below:
 - Determines how schedule is modified
 - Based on available time, act. type, resolution type, etc.
 - Insert new activity or drop depending on results

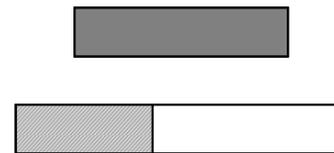
Case 1: Inserted Original



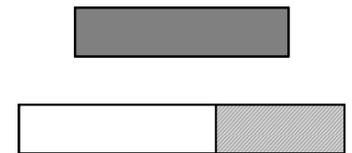
Case 2: Overlapped Original



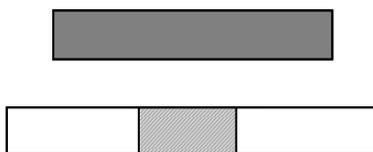
Case 3: Overlap Start



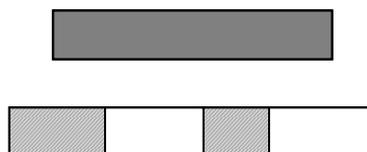
Case 4: Overlap End



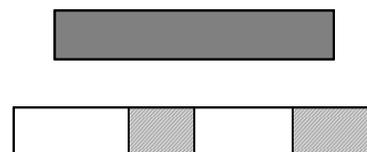
Case 5: Overlap End & Start



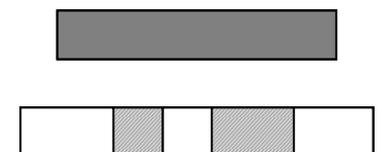
Case 6: Insert & Overlap Start



Case 7: Overlap End & Insert

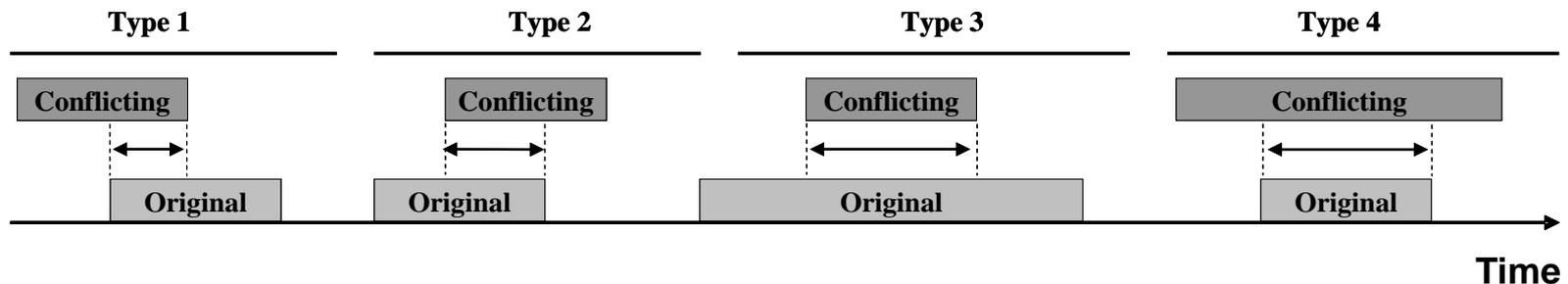


Case 8: Insert/Overlap Start /End



Scheduling - Conflict Resolution

- Due to dynamic nature of scheduling, conflicts naturally arise
 - Timing, location, resource
- Conflict resolution model chooses strategy for resolving conflict
 - Currently only for timing
 - Uses decision trees
 - Strategies based on demographics, constraints, schedule characteristics, etc.

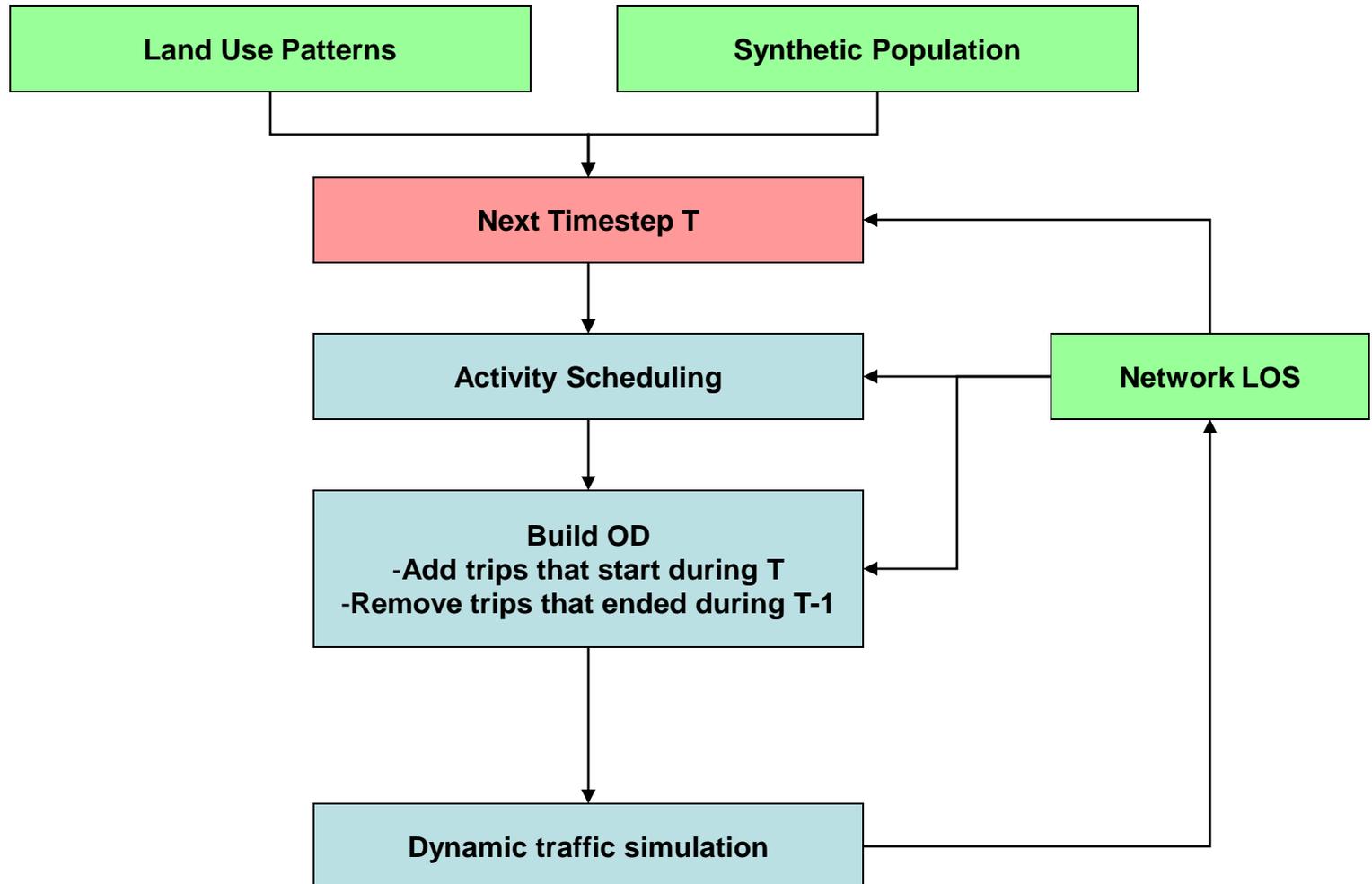


Integration with Traffic Assignment

Integration with Traffic Simulation

- Integration of activity planning/scheduling with traffic assignment
 - As activities are executed generate trip vector
 - Pass to dynamic traffic assignment routine
 - Return locations of each individual at end of timestep
 - Simulates 15 minutes of travel
- Currently testing a number of DTA programs
 - Needs to be able to interact with ADAPTS scheduler
 - Capable of simulating short time periods
 - Many options to test: Dynasmart, Dynamit, Vista, Transims, Aimsun, etc.

Integration with Traffic Simulation



Cordon Pricing Simulation Example

Cordon Pricing Simulation

- Two small-scale ADAPTS simulations have been run for Chicago
 - Baseline scenario: using current LOS
 - Pricing scenario: cordon pricing around downtown in AM and PM peak periods
- Created to demonstrate important features of ADAPTS
 - Determine policy sensitivity
 - Demonstrate dynamic activity planning

Simulation – Cordon Pricing

- AM and PM peak cordon pricing
 - 7-10 AM and 3-6 PM
 - All trips entering downtown (TAZ 54-128)
 - Toll of \$10 to enter cordon area
 - No toll within cordon or for outbound trips

Simulation Comparisons

BEFORE CORDON PRICING

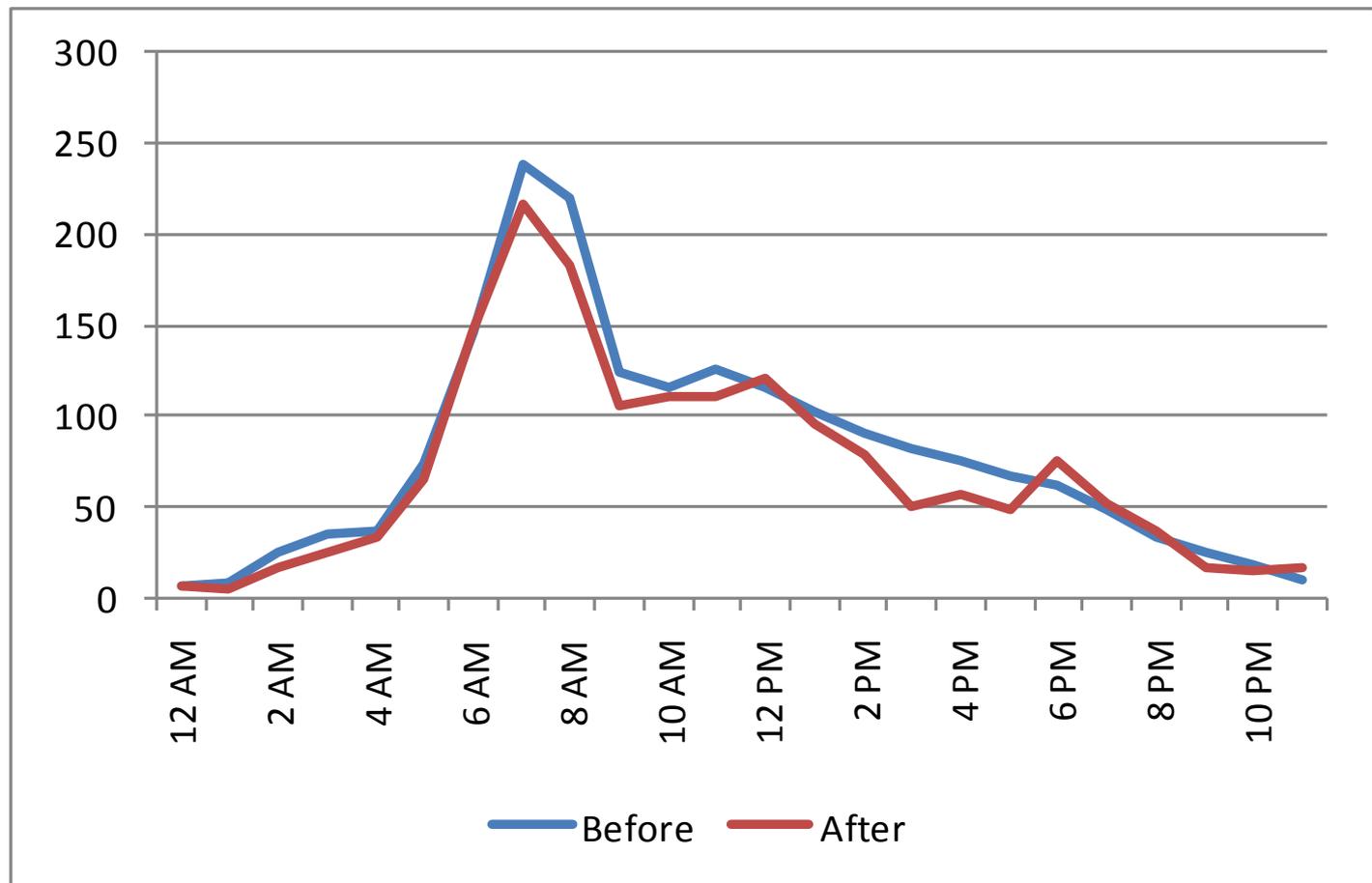
	Mode Distribution			Destination Distribution
	Auto	Walk/Bike	Transit	
DOWNTOWN	57%	17%	26%	6.3%
COOK	82%	11%	7%	48.5%
DUPAGE	93%	5%	2%	15.1%
KANE	94%	6%	1%	8.3%
LAKE	93%	5%	2%	9.2%
MCHENRY	94%	6%	0%	5.1%
OTHER	95%	5%	0%	0.4%
WILL	94%	5%	0%	7.0%
Grand Total	86%	9%	5%	100%

AFTER CORDON PRICING

	Mode Distribution			Destination Distribution
	Auto	Walk/Bike	Transit	
DOWNTOWN	51%	16%	33%	5.7%
COOK	82%	12%	6%	49.0%
DUPAGE	93%	5%	2%	15.2%
KANE	94%	6%	1%	8.1%
LAKE	93%	5%	1%	9.3%
MCHENRY	94%	6%	1%	5.1%
OTHER	94%	6%	0%	0.4%
WILL	95%	4%	0%	7.2%
Grand Total	86%	9%	5%	100%

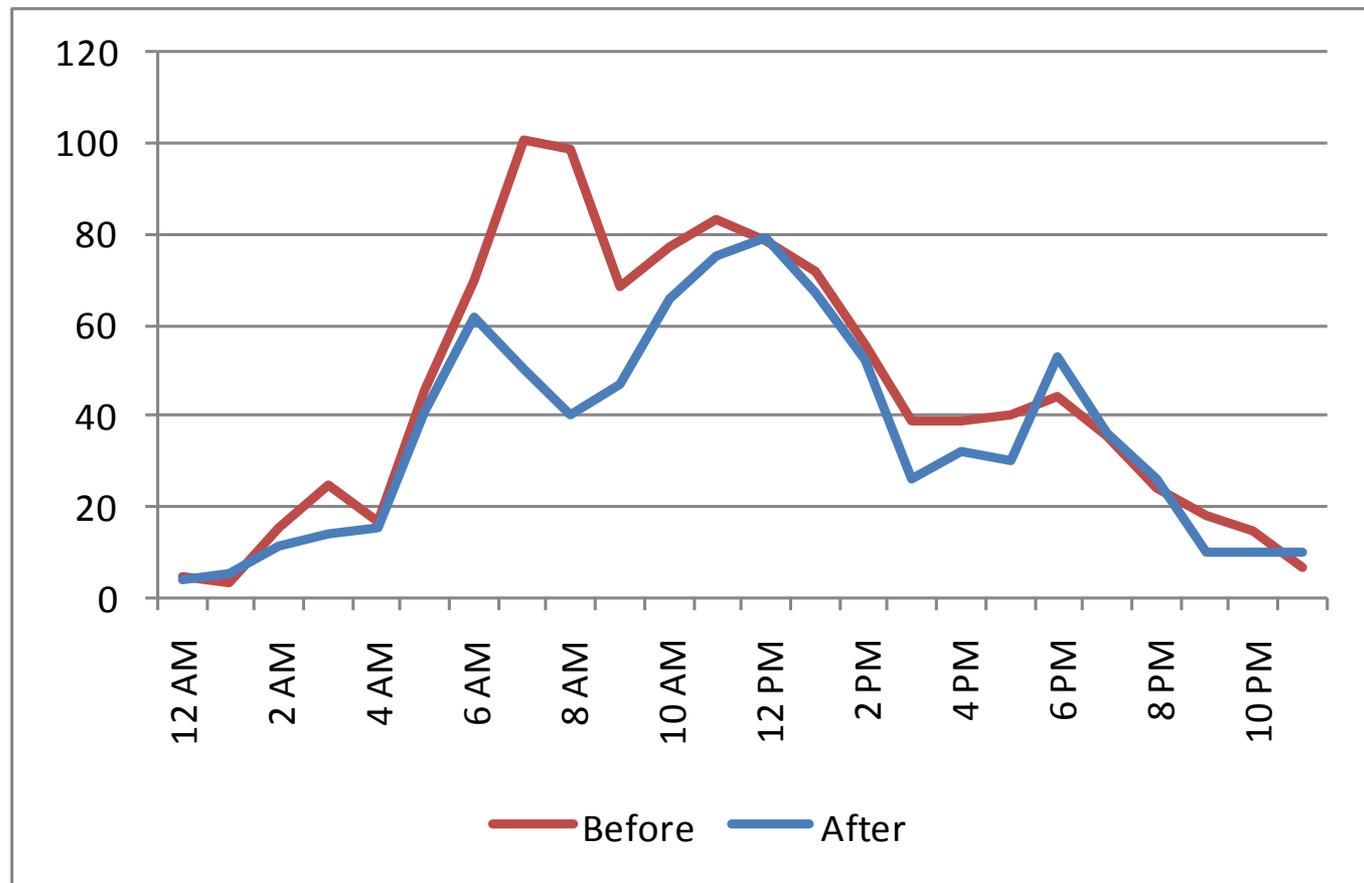
Simulation Comparisons

- Demand by hour for all Trips to Downtown



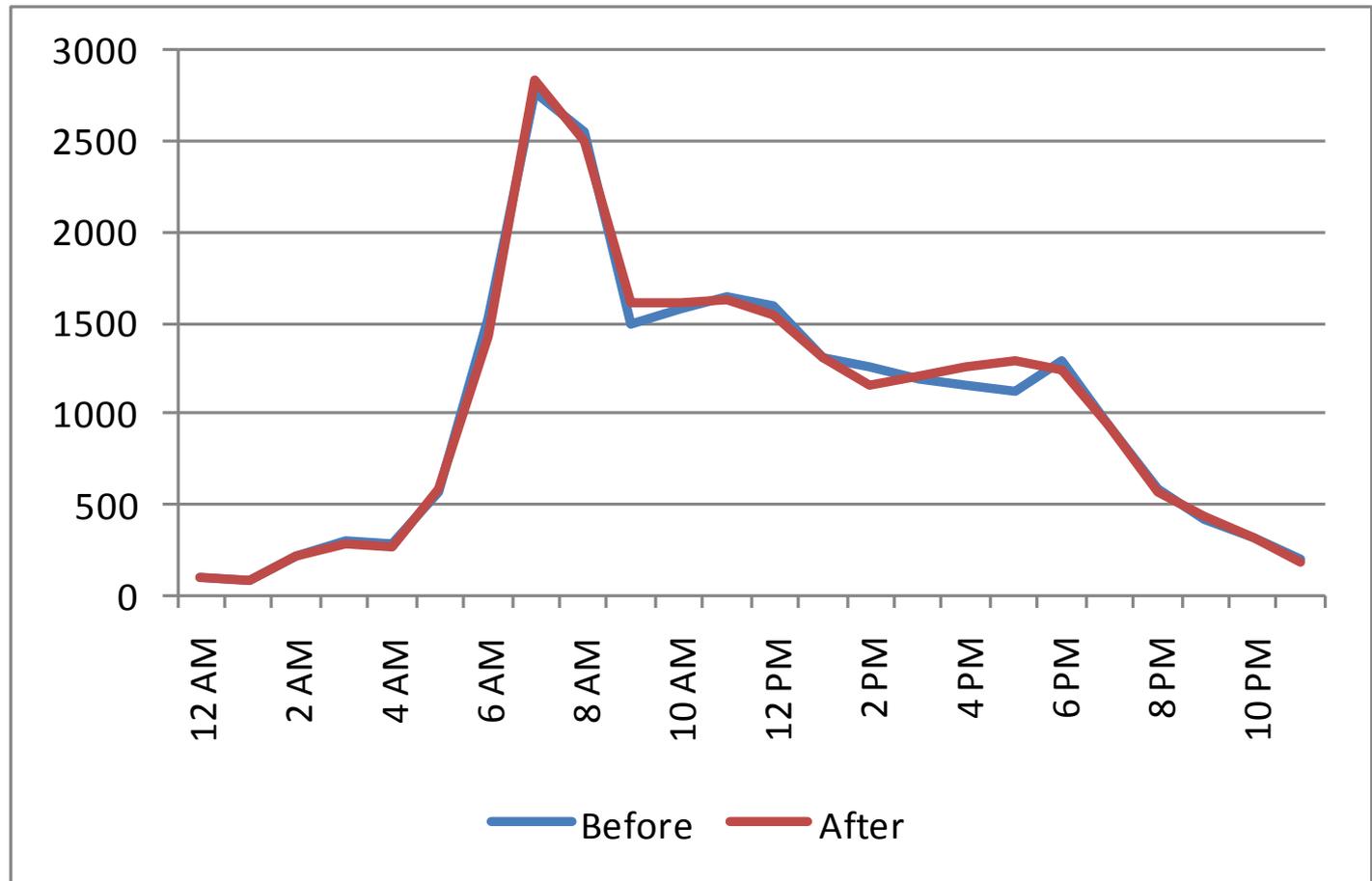
Simulation Comparisons

- Demand by hour for Auto Mode Trips



Simulation Comparison

- Demand for non-downtown auto trips by hour



Simulation Discussion

- Representation of complex response to cordon pricing policy
 - Desired effect of decreased auto-demand during peak periods to downtown
 - Effects continue after pricing ends – due to trip chain effect (no autos for secondary trips)
 - Side effect of increased auto-demand overall
- Simplified models with aggregate results
 - No feedback, learning, etc. in LOS representation
 - Reevaluate when ADAPTS completed
 - Need to observe results at disaggregate geographies

Conclusion



Discussion and Conclusions

- ADAPTS framework represents dynamics of activity planning
 - Dynamic activity generation (when completed)
 - Conditional attribute planning (from plan order model)
- Plan order model sets when planning decisions made
 - Correlated responses give more realistic planning order
 - Linked directly to key policy variables
 - Allows conditional attribute planning
- Flexible activity scheduling with conflict resolution
 - No predetermined order of activities entering schedule

Discussion and Conclusions

- Promising initial simulation results
 - Demonstration of trip-chaining effect
 - Demand shift due to pricing
- Future work:
 - Integration of plan horizon responses to simulation time
 - Development of rest of attribute models
 - Test impact of planning behavior changes on travel demand
 - Link to traffic simulation/assignment

Thank You!
Questions?

Funding provided by:



National
Science
Foundation

IGERT

*Integrative Graduate
Education and
Research Traineeship*

**IGERT Ph.D. Program in
Computational Transportation Science**

